# THE CHARACTERISTICS OF THE OPERATING PARAMETERS OF THE VERTICAL AXIS WIND TURBINE FOR THE SELECTED WIND SPEED

Zdzisław Kamiński<sup>1</sup>, Zbigniew Czyż<sup>1</sup>

<sup>1</sup> Department of Thermodynamics, Fluid Mechanics and Aviation Propulsion Systems, Faculty of Mechanical Engineering, Lublin University of Technology, 36 Nadbystrzycka Str., 20-618 Lublin, Poland, e-mail: z.kaminski@pollub.pl, z.czyz@pollub.pl

Received: 2016.12.15 Accepted: 2017.02.01 Published: 2017.03.01

#### ABSTRACT

The article presents the results of examining a wind turbine on the vertical axis of rotation. The study was conducted in an open circuit wind tunnel Gunt HM 170 in the laboratory of the Department of Thermodynamics, Fluid Mechanics and Aviation Propulsion Systems at Lublin University of Technology. The subject of research was a rotor based on the patent PL 219985, with blades capable of altering the surface of the active area (receiving kinetic energy of the wind). The study was performed on appropriately scaled and geometrically similar models maintaining, relevant to the type of research, the criterion numbers. The studied rotors with different blade inclination angles were produced using a 3D powder printer ZPrinter<sup>®</sup> 450. The results of the conducted research were obtained for the flow velocity of 6.5 m/s and three inclination angles, 30°, 60°, and 90°, at variable rotational speed. The test equipment used in the study allows maintaining the required speed, recording velocity and torque, which in turn allows an engineer to measure such characteristics of torque and power as a function of rotor speed.

Keywords: wind turbine, renewable energy, wind tunnel, drive torque, power.

#### INTRODUCTION

Wind energy is the energy that comes from the sun. The phenomenon of the wind is related primarily to the uneven heating of air masses by solar radiation, uneven surface of land and Earth's rotation. Conversion of kinetic energy derived from moving air masses into mechanical energy is done using a wind turbine or wind turbines complex. The energy produced in this way can be used to perform certain tasks (e.g. pumping water) or using a generator to produce electricity. First attempts to generate electricity using wind were undertaken in the nineteenth century, but only in recent years did this method start to be used on a larger scale. To use wind energy to generate electricity certain conditions must be met constant wind with definite speed. Wind turbines usually operate at wind speed rates of 5 to 25 m/s, and the speed of 15 to 20 m/s is considered optimal. Inadequately low speeds are insufficient for the production of electric energy of adequate power, while too high ones (over 30 m/sec) can lead to mechanical damage to the rotor. The location of the wind power plant is also important because it must take into account the roughness of the terrain and the impact of natural obstacles on wind flow. Rotors should not be located in a turbulent area where air turbulence reduces efficiency of power stations and can furthermore disturb its construction. The average wind speed in Poland is 3.4 m/s in the summer months, and 3.8 m/s in the winter months. It is worth noting that the seasonal wind energy resources coincide quite well with the maximum demand for thermal energy, which is the period of the lowest temperatures [16]. Wind energy is an important, environmentally friendly source of energy, which has be-



Fig. 1. The number of articles on optimization of wind turbines in the last 20 years [4, 9]

come increasingly important in recent years. The number of wind turbines installed every year is growing, and a lot of countries plan to invest in wind power in the near future [29].

Harnessing wind power is generating considerable interest, modern wind turbines begin to sell electricity to power networks [18, 23]. A constantly growing interest in wind turbines also results from the rising number of scientific works published every year. In determining the actual power, wind power plants must consider the mechanics of incoming wind mass flow on the rotor, aerodynamics of rotor planes and the efficiency of the rotor [10, 19, 32, 33]. The yield depends on the wind turbine power coefficient Cp, which determines how much power stored in the flowing air is converted by the wind turbine. The theoretical maximum power factor is determined by what is referred to as Betz' limit and is equal to 0.59 for an idealised wind turbine [25]. The issue of increasing the efficiency of wind turbines is a highly complex problem connected with optimization. Researchers have developed a variety of tools, methods, algorithms and models to optimise wind turbines. On the base of Scopus the authors [4], [9] have shown an exponential growth in the number of articles which explicitly raise the subject of wind turbines optimization (Figure 1).



**Fig. 2.** 3D models of rotors of a wind turbine designed with an opening angle equal to the working surfaces, (from the left) 30°, 60°, 90° respectively [6]



Fig. 3. Dimensions of the rotor (blade inclination angle 90°)

The subject of optimization, and particularly the subject of reducing the cost of generation of energy (COE cost of energy) is referred to in [1, 2, 4, 7, 8, 11-15, 17, 22, 24, 27, 34, 35].

Currently, there are over 300 patents on various solutions regarding vertical-axis wind turbines (VAWT). The majority of those concern small power plants that can be used for the needs of individual customers. The main disadvantage of wind turbines with a vertical axis of rotation is virtually zero starting torque required for initial start-up. To eliminate this inconvenience numerous design modifications of turbines have been introduced, which were predominantly associated with the use of variable blade angles or the position of rotor blades [3]. An example of an innovative solution to eliminate the above drawbacks is the proposed vertical-axis model of adjustable working surface of rotor blades. This solution was granted a patent in the Polish Patent Office [31].

The testing of wind turbine with working surface inclination angles equal to  $30^\circ$ ,  $60^\circ$ ,  $90^\circ$  were performed using CATIA v.5 (Fig. 2). Due to minimization of the research object conditioned by



**Fig. 4.** Wind tunnel GUNT model HM 170, 1 - inlet contour, 2 - flow straightener, 3 - nozzle, 4 - measuring section, 5 - drag body, 6 - force sensor, 7 - display and control unit, 8 - diffuser, 9 - switch cabinet, 10 - inclined tube manometer, 11 - axial fan [20]

overall dimensions of the wind tunnel measuring space, it was decided to perform stable/permanent rotors (with 0°blade inclination angle) in order to simplify the prototypes of test objects. Based on experience gathered in the construction of a model, it was established that the rotors will be produced on a powder printer ZPrinter® 450. This is due to, inter alia, criteria of accuracy, aesthetics and execution time. Printed rotors were hardened with cyanoacrylate adhesive, and polished appropriately to give a smooth work surface. The applied technology is described in [5, 6].

Figure 3 shows dimensions of the rotor of a working surface inclination angle of 90°.

# **TEST SET-UP**

Wind tunnel, often equipped in specialist measuring systems, constitutes a basic tool in experimental aerodynamics (Figure 4). Depending on the application, it allows to transfer the results of model tests to objects in the real scale, taking into account criteria of similarity and appropriate correction factors. The study used an open circuit tunnel, HM 170 GUNT, with a closed measurement space. Basic specifications of the tunnel are shown in Table 1. Such a system imposes limitations due to interference with the walls of the tunnel and the horizontal pressure gradient dp/dx. On the other hand, the advantage is reduced pressure pulsation and lower flow resistance. The use of the tunnel for testing consists in that the object tested is at rest while the air is set in motion, and thus the desired air flow around the model is generated by a fan placed inside. The air is sucked in from

**Table 1.** Basic parameters and their values characteris-tic of the wind tunnel GUNT model HM 170 [20]

Parameter name or technical properties	Size parameter
The cross section of the test chamber (width x height)	292 x 292 mm
Length	450 mm
Maximum velocity of the air stream	28 m/s
The pressure differential	500 Pa
Maksimum volume flow	9000 m³/h
Power of electric motor	2.25 kW
Maximum fan speed	2850 obr/min
Range of force measurement	0-5N i 0-10 N
Range of pressure measurement	0-500 Pa

the atmosphere and accelerated in the converging channel 3 and then flows around the model in measuring section 4. Behind the test chamber there is a diffuser 8 where the air speed is reduced and the air is pumped to the open air by the axial fan 11. A carefully designed outline of flow straightener ends 2 provides uniform velocity distribution with little turbulence in the closed measurement part. The built-in axial fan with a steering wheel and variable speed drive allows energy-efficient operation at high efficiency. Maximum air speed that can be generated in the wind tunnel is 28 [m/s].

The applied turbine testing system is shown in Figures 5 and 6. Exchangeable rotors 4 are mounted to the vertical axis of turbine 2 (Figure 6). The outer part of the mast was modelled and printed on a 3D printer, and axis 2 (Figure 6) is made of carbon fibre and mounted on roller bearings. To the axis (below the measurement section) an electric DC motor 4 was mounted (Figure 6), acting as a brake.

Brake assembly is a major component of the test system of the wind turbine. The electric motor 4 (Figure 6) loads/charges the turbine rotor to produce torque opposite to the movement of rotor blades. The electric motor is fastened to a 50-mm-long lever 5 which produces pressure on the strain gauge beam 6 (Figures 6 and 7).



Fig. 5. The test turbine: 1 – data recording, 2 - a set of thermo-anemometric sensors, 3 – wind tunnel measuring space, 4 – a set of examined rotors of wind turbine, 5a - wind turbine assembly, 5b - brake assembly of the turbine, 6 – a unit managing thermoanemometers ATU-08, 7 - PC, 8 - Compact DAG Slot USB Chassis NI CDAG-9178 with measuring cards: NI 9215 (measuring the rotational speed of the rotor turbine), NI 9237 (force measurement), 9 - laboratory power supply R & S®HMP4040



Fig. 6. Wind turbine brake set: 1- supporting structure of the turbine, 2- the turbine vertical axis turbine 3- optical sensor for rotational speed measurement
4- electric motor loading the turbine, 5- lever exerting force on the strain gauge, 6- foil strain gauges stuck on the beam 7- the strain gauge handle

The strain gauge beam is composed of 0.5 mm x 15 mm steel sheet, with attached four foil strain gauges TENMEX TF3 / 120-W [20] stuck to it, and is shown in Figure 7 and Table 2.

The turbine brake set cooperates with a computer-aided processing of measurementcontrol data. Measurement signals are acquired by means of the system consisting of National Instruments Compact DAQ 9172 chassis with NI 9215 (rotational speed measurement of the turbine rotor performed with RMS) and NI 9237 measurement cards (force measurement) shown in Fig. 8, and a netbook with data recording and processing software.

Data acquisition and pre-processing was carried out using measurement software and software for test results analysis. Both programmes were executed in LabVIEW 8.1 (Laboratory Virtual Instrument Engineering Workbench), which is a product of National Instruments Corporation. LabVIEW is a programming environment for creating personalised utility programmes, such as Borland C, Borland Pascal etc. The main difference is the way the source code of the pro-

**Table 2.** The characteristics of a foil strain gaugeTENMEX TF3 / 120-W

Sensor type	Strain gauge foil	
Working temperature	-40 ÷ 200°C	
Properties of sensors	constant strain gauge 2.15	
External dimensions	5x7.5x0.06mm	
Max. deformation	5%	
Tolerance	± 0.5%	
Terminal	silver pin	
Resistance	120 Ω	

 Table 3. Characteristic data of measurement card NI

 9215 [26]

Measurement conditions	Gain error	Compensation error
Calibrated max. (-40 ÷ +70°C)	0.2%	0.082%
Calibrated type (25 ± 5°C)	0.2%	0.014%
Not calibrated max. (-40 ÷ +70°C)	1.05%	0.082%
Not calibrated type (25 ± 5°C)	0.6%	0.38%

**Table 4.** Characteristic data of measurement card NI9237 [26]

Measurement conditions	Gain error	Compensation error
Calibrated max. (-40 ÷ +70°C)	0,20%	0,25%
Calibrated type (25 ± 5°C)	0,05%	0,05%
Not calibrated max. (-40 ÷+70°C)	0,60%	0,35%
Not calibrated type (25 ± 5°C)	0,20%	0,1%

gramme is created. In other environments, the source code is a sequential text representation in a specific programming language (Basic, C, Pascal), while in LabVIEW the source code comes down to graphic representation of the input function (from keyboard and instruments), output (screen, printer and instruments), transferring and processing information, and the con-



Fig 7. Foil strain gauge TENMEX TF3 / 120-W [21] and a strain gauge beam



Fig. 8. Chassis National Instruments Compact DAQ 9172 with measurement cards NI 9215 and Ni 9237 [26]



Fig. 9. Block diagram of data measurement and recording software

nection between blocks. Graphic language G shows the recording of the program in the form of icons, clamps and connections, through which virtually any gauge can be built. Depending on your needs and the software, it can be a virtual oscilloscope, spectrum analyser, recorder, multimeter or any other type of device.

LabVIEW has an extensive library of functions and subprograms for most programming tasks. Moreover, it includes a rich library of software drivers for various measuring instruments, interface drivers GPEB, VXI and serial and function libraries for the collection, analysis and presentation of data. LabVIEW, as well as other programming environments, gives many possibilities to run the programme in search of errors. The software allows an engineer to set traps, animate the diagram of information flow, as well as run the programme step by step, in order to track the results in different parts of the programme [28, 30]. A view of the block diagram of the programme for recording measurement data is shown in Figure 9.

# RESULTS

Figure 10 presents the characteristics of lever pressure on the strain gauge beam as a function of speed for wind velocity equal to 6.5 m/s.



Fig. 10. Lever pressure on the strain gauge beam as a function of rotational speed for the examined angles of working blades



Fig. 11. Power characteristics of the test turbine rotor as a function of rotational speed for examined angles of working blades

Test measurement points obtained during the research are approximated by the least squares method by means of Approximation v1.5.9.2 programme. As a result 4<sup>th</sup> degree polynomials shown below were obtained, respectively for tested working surface inclination angles of the rotor turbine, i.e.  $30^{\circ}$ ,  $60^{\circ}$  and  $90^{\circ}$ . The chosen degree of the polynomial is the one producing the least errors.

$$F_{30} = F_{30}(n) = 3,83886103864611E - 10 \cdot n^4 - 5,13140787635671E - 7 \cdot n^3$$
(1)  
+0,000137710478732145 \cdot n^2 - 0,128905892843642 \cdot n^1 + 92,6091338495036 \cdot n^0

$$F_{60} = F_{60}(n) = -2,79984594380679E - 9 \cdot n^{4} + 4,54993308532521E - 6 \cdot n^{3} -0,00264932926795291 \cdot n^{2} + 0,335491632864947 \cdot n^{1} + 191,420547278695 \cdot n^{0}$$
(2)

$$F_{90} = F_{90}(n) = 9,97050177669547E - 9 \cdot n^{4} - 1,59095357559089E - 5 \cdot n^{3} - 0,00776435915542609 \cdot n^{2} - 1,53073906112335 \cdot n^{1} + 346,316994093761 \cdot n^{0}$$
(3)

The torque M of turbine rotor was determined from the equation (4):

+

$$M = F * \mathbf{r} \tag{4}$$

where: M - torque [Nm]; F- force on the strain gauge [N]; r - radius of force F [m].

The power P generated by the turbine rotor was determined from the equation (5):

$$P = \frac{M*n}{9550} * 10^6 \tag{5}$$

where: P - power generated by the rotor [mW]; n - rotor speed [r / min].

Below you can see characteristics of the power of the test turbine rotor as a function of rotational speed for the three angles of working blades, respectively:  $30^\circ$ ,  $60^\circ$ ,  $90^\circ$ .

$$P_{30}=P_{30}(n) = -4.6393220204193SE - 10 \cdot n^4 + 4.58900150626661E - 7 \cdot n^3$$
(6)  
-0.000237719732272211 \cdot n^2 + 0.0760979181168856 \cdot n^1 - 1.41262596576373 \cdot n^0

$$P_{60} = P_{60}(n) = -4.29813812920552E - 10 \cdot n^4 + 6.08578392385269E - 7 \cdot n^3 - 0.000465184990199032 \cdot n^2 + 0.190227702685209 \cdot n^1 - 4.21801339864675 \cdot n^0$$
(7)

$$P_{90}=P_{90}(n)=2.69486778935756E-9\cdot n^{4}-4.81178368174605E-6\cdot n^{3}$$
  
+0.00258607612024464\cdot n^{2}-0.428357438534595\cdot n^{1}+41.2989304374826\cdot n^{0}
(8)

On the basis of the characteristics of the test turbine power as a function of rotor rotational speed for the investigated blade angles (Figure 11), maximum values of the power generated in the tested range were set. This makes it possible to chart the generated power as a function of the rotor working blades inclination angle. Figure 12 shows the effect of inclination angle on the generated power. (0,0) was added to the points obtained in the test characteristic point to define a zero value of the full closure of working blades (inclination angle 0°) because of zero rotor working surface inclination.

The dependence of the effect of the blade inclination angle and the value of power generated is described by the equation 9.



Fig. 12. Power of the test turbine as a function of blade inclination angle



**Fig. 13.** The increase in power generated by the blade angle of  $60^{\circ}$  and  $90^{\circ}$  relative to the blade angle of  $30^{\circ}$ 

 $P=P(\alpha) = -2,9876543209877E - 5 \cdot n^{3} + 0,00700555555555555562 \cdot n^{2} + 0,110388888888866 \cdot n^{1} + 1,89852340524411E - 14 \cdot n^{0}$ (9)

Figure 13 shows the increase in power generated exhibited at rotor inclination angles  $60^{\circ}$  and  $90^{\circ}$  compared to the blade inclination angle of  $30^{\circ}$ .

#### CONCLUSIONS

Test results, based on the functions approximating power depending on the speed of rotation, indicate that the rotor at an inclination angle of 30° reaches maximum speed n<sub>max</sub> = 480 rpm at a wind speed v = 6.5 m/s. At this speed (idling) the rotor generates power of 6.4 mW. During braking, the rotor has reached maximum power equal to 8.81 mW at a speed n = 350 rpm. With reference to the minimum value of power generated by the rotor the result shows an increase of 278% (in the tested range). Further braking the rotor below the speed n =350 rpm reduces the power. Measurements of rotor inclination angle of 30° were carried out at the rotational speed  $n_{min} = 81.7$  rpm, at which the obtained power equals to 3.45 mW.

The rotor with inclination angle of  $60^{\circ}$  reaches the maximum speed  $n_{max} = 641$  rpm at a wind speed v = 6.5 m/s. At this speed (idling) the rotor generates power at the level of 14.27 mW. During braking, the rotor has reached the maximum power equal to 25.39 mW at the speed n = 401 rpm. With reference to the minimum value of the power generated by the rotor it exhibits an increase of 342.9% (in the tested range). Further braking the rotor below the speed n = 401 rpm reduces the power. Measurements of rotor inclination angle of  $60^{\circ}$  to the rotational speed were carried out to rotational speed  $n_{min} = 73.7$  rpm when the power equals to 7.5 mW.

The rotor with inclination angle of 90° reaches the maximum speed  $n_{max} = 696$  rpm at the wind speed v = 6.5 m/s. At this speed (idling) the rotor generates power of 5.98 mW. During braking, the rotor has reached the maximum power equal to 44.9 mW at the speed n = 426.46 rpm. With reference to the minimum value of power generated by the rotor it denotes an increase of 792.6% (in the tested range). Further braking the rotor below the speed n = 426.46 rpm reduces the power. Measurements of rotor inclination angle of 90° were carried out to the speed  $n_{min} = 174$  rpm, the obtained power equals to 22.1 mW.

The evidence from this study implies that depending on the inclination angle of the working blades, it is possible to adjust the value of power input in the range of 0 mW (with blades fully closed) to 44.9 mW with inclination angle of the working blades of 90°. The mechanism of adjusting the inclination angle of working blades allows for smooth shift of the angle and simultaneously smooth change of power generated.

Our findings show that the larger the inclination angle the higher values of rotational speed are achieved. In order to make a comparative analysis of the results for different angles of inclination, only the speed range of 174 rev/min to 480 rev/min was taken into account. These values correspond respectively to the minimum rotational speed recorded for 90° and the maximum speed value recorded for  $30^{\circ}$  (Fig.11). If we increase the inclination angle in the specified speed range from 30° to 60°, then the increase in the power generated will amount to 166% in the initial range and constantly growing with the rotational speed, until the end of the range where the power will increase by 277%.

If, however, the inclination angle increases from  $30^{\circ}$  to  $90^{\circ}$ , then at the initial range the power will increase by 235% and growing with rotational speed at the end of the range, the power will increase by 556%.

Rotor blades with adjustable positions of blades allow the power of the turbine to be regulated over a wide range of values (of the main shaft or of the turbine) depending on wind speed and direction. This advantage prevents the destruction of components of the turbine in the event of high winds. This form of protection allows keeping a unit of turbine rotor in continuous operation and keeps the speed constant, which is important from the point of view of operating an electric generator. This makes it possible to obtain a constant value of power generated regardless of changes in wind speed (within a specified range) or it can work at optimum points, i.e. where the greatest amount of energy can be produced.

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