

## Conception of Hollow Axles Forming by Skew Rolling with Moving Mandrel

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### ABSTRACT

The article presents a conception of manufacturing a hollow axle using three skewed rolls moving at the same rotating speed, axially moving chuck and a moving mandrel. The outer shape of the axle is obtained as a result of combining the radial feed of the rolls with axial feed of the chuck. The hole in the axle, however, is obtained as a result of the mandrel acting on the workpiece while moving along with it. In order to assess the correctness of the presented concept of forming, a numerical simulation was performed in Simufact. Forming commercial software. The results of the simulation confirmed that the applied method allows one to manufacture large-size hollow axles. Moreover, information on force parameters of the forming process, which can be used for designing an industrial rolling mill was obtained.

**Keywords:** hollowed axle, skew rolling, FEM.

### INTRODUCTION

Hollow axles and shafts are increasingly common in automation and machine industry, due to the fact that their mechanical properties are comparable to the ones of solid elements, while offering a significantly lower mass. Currently, such elements are manufactured using one of the following methods [1]: machining, metal forming, casting and powder metallurgy.

Metal forming methods are especially popular in the case of manufacturing hollow elements. They are highly effective, allow one to enhance mechanical properties as well as to decrease energy and material consumption of the manufacturing process. Currently, hollow elements are manufactured using the following methods: roll forming, cross-wedge rolling (CWR), forging on swaging machines, hydroforming, extrusion and spinning [1].

Lately, intensive research on new methods of forming large-size axles and shafts, used e.g. in heavy-loaded trucks or railway wagons was carried out. Such elements are most often manufactured by forging on swaging machines [2]. In

order to increase forming effectiveness, technology of cross-wedge rolling was examined. The main issue with CWR is the length of the rail axles, reaching 2.5 m. Rolling such elements in the traditional manner would require using rolling mills with the diameter of rolls exceeding 2 m, which is not available on the market.

In order to decrease the length of the tools (decreasing roll diameter) Shu et al. [3] proposed a multi-wedge rolling method, in which the axle is rolled by a few pairs of wedges simultaneously. A drawback of this method is an excessive ovalisation of the cross-section, which may cause the workpiece to axially fracture in the case of whole elements. In order to eliminate this phenomenon Pater and Tomczak [4] proposed a two-stage rolling method. In the first stage, the central part of the axle is formed with one pair of rolls, whereas in the second one another pair of rolls forms side steps of the axle. Such a solution allows one to decrease the nominal diameter of the rolls to an acceptable value, equal 1200 mm. An alternative solution proposed by Pater [5] consisted of introducing

special undercuts to the calibrating part of the tools, which would reduce excessive ovalisation of the cross-section of the workpiece.

In the case of hollow axles it is necessary to control the inner diameter using a cylindrical mandrel. Its usage, however, facilitates excessive deformation of the cross-section of the workpiece [6, 7]. An important aspect of designing the CWR process for hollow elements is an accurate choice of the angles of the wedge, mainly the forming angle and spreading angle. On the basis of the analyses performed [8, 9] it was stated that in the case of forming hollow elements tools with smaller spreading angle and greater forming angle ought to be used. Lately, studies [10, 11] indicating the validity of employing three rolls in skew rolling processes of hollow elements. In this type of rolling, deformations of the cross-section of the workpiece is significantly smaller than in the case of two-roll rolling. These conclusions, however, are based purely on theoretical considerations.

The lately developed method of skew rolling in a CNC rolling mill seems promising in terms of forming long stepped axles and shafts. This method is highly universal. The same set of three rolls allows one to manufacture axial-symmetric elements of various shape [12, 13]. This indicates that this method can be used in small-scale production. The first attempts at rolling full rail axles in 1:5 scale in laboratory conditions confirmed another benefit of this process, that is relatively

small (compared to the dimensions of the work-piece) values of forming forces and torque. This results in small energy consumption of the manufacturing process as well as light construction of the rolling mill. The latest numerical analyses [16, 17] indicated that this method would allow one to manufacture hollow rail axles.

This paper presents a new concept of skew rolling large-size hollow axles in a CNC rolling mill. The innovation of this solution is the usage of a moving mandrel, which influences the inner diameter of the workpiece. The correctness of the assumed forming concept was proven using a numerical simulation.

### THE PRINCIPLE OF THE PROPOSED FORMING PROCESS AND ITS NUMERICAL MODEL

The innovative method of forming hollow elements was presented using the example of an axle shown in Figure 1. It is a rail axle with a cylindrical hole with a  $\varnothing 80$  mm diameter. For the rolled axle, two technological allowances were assumed. One of those is linked to fastening the billet in the chuck, whereas the other is connected to the rolls leaving the forming zone. The allowances shall be removed from the axle after the forming process.

Figure 2 presents the scheme of axle rolling using five tools. The most important ones are three identical rolls skewed in relation to the axis of the workpiece,

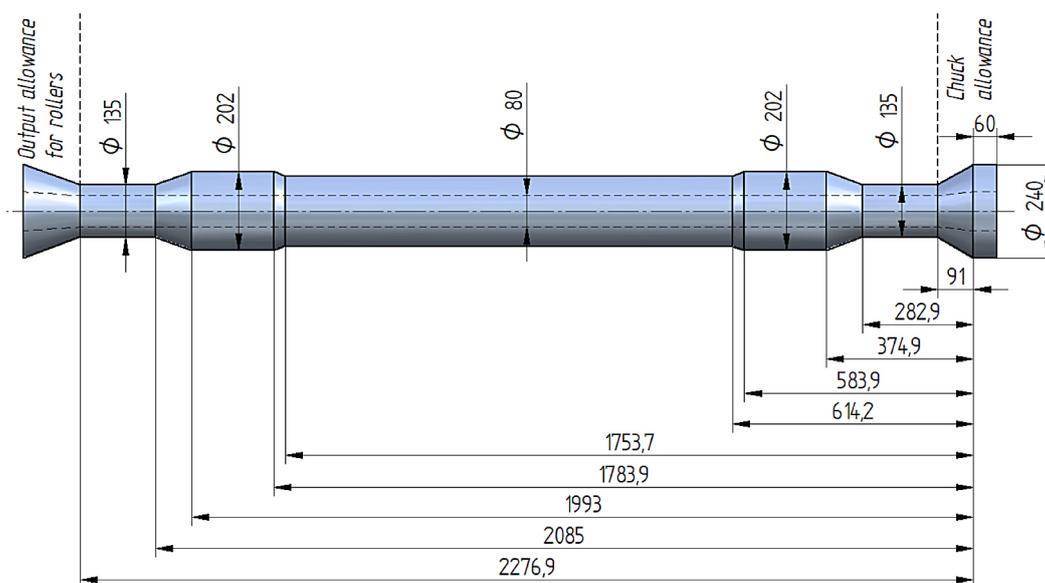


Fig. 1. Forging of a hollow axle with technological allowances, necessary for the process of skew rolling with a mandrel

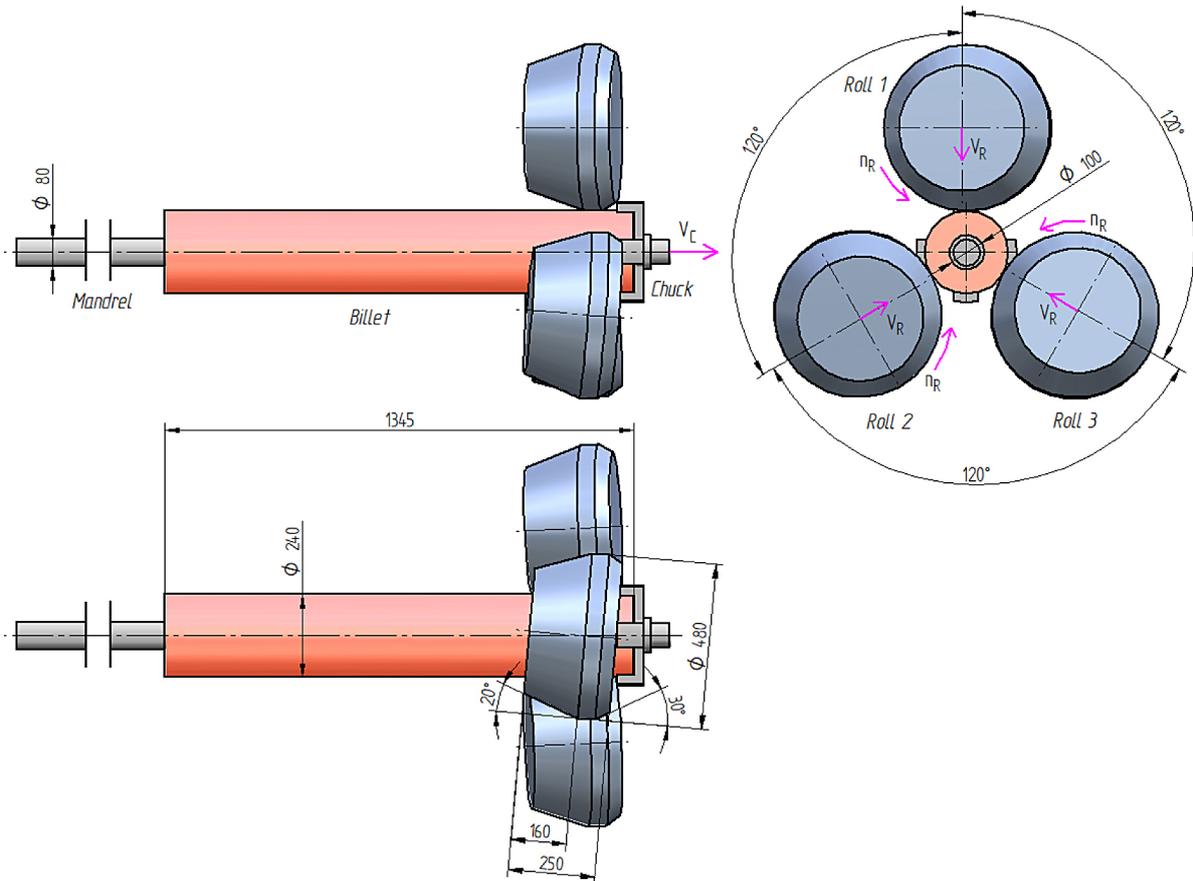


Fig. 2. Scheme of the process of skew rolling with a mandrel of a hollow axle; important dimensions given

rotating at the constant speed of  $n_R$ . Moreover, the tools can move in the radial direction at the speed of  $v_R$ , as a result of which the diameter of the rolled step might be changed. An important tool to this process is the chuck, moving at the speed of  $v_C$  and controlling the axial dislocation of the workpiece. In order to obtain the assumed shape of the workpiece, it is necessary to properly establish  $v_C$  and  $v_R$ . The last tool is a cylindrical mandrel longer than the formed axle, which aims to hinder radial material flow. The

mandrel can rotate as well as move axially, but the movement is caused by the workpiece.

In order to prove the correctness of the presented forming concept a numerical model presented in Figure 3 was built in Simufact. Forming software. The shape and dimensions of the tools modelled as perfectly rigid bodies are in accordance with Figure 2. The billet is a sleeve with the outer diameter equal  $\phi 240$  mm, inner diameter  $\phi 100$  mm and length equal 1345 mm.

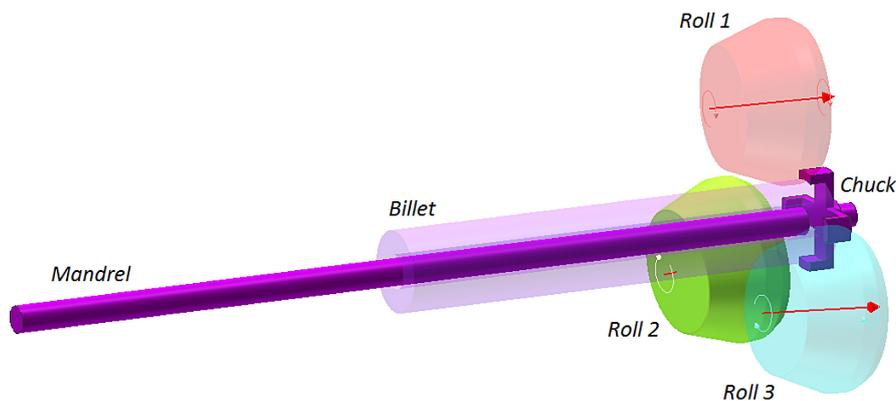


Fig. 3. Geometrical model of skew rolling of a hollow axle, prepared in Simufact. Forming v. 15

It was assumed that the rolls rotate at the constant speed of  $n_R = 60$  rpm throughout the rolling process. Axial displacement of the chuck  $v_C$  was also deemed to be constant. In Figure 4 it is compared to the radial speed  $v_R$  of the rolls. With such kinematic parameters, the forming time for an axle equalled c.a. 45 s.

The hollow axle is made of 42CrMo4 grade steel. The material model of this steel, taken from the library database of the employed software is described with the following equation :

$$\sigma_F = 4628.8e^{-0.00345T} \varepsilon^{(-0.00000509T-0.03638)} e^{(-0.00000461T-0.01944)/\varepsilon} \dot{\varepsilon}^{(0.0001893T-0.04627)} \quad (1)$$

where:  $\sigma_F$  is flow stress, MPa;  $\varepsilon$  is effective strain, -;  $\dot{\varepsilon}$  is strain rate,  $s^{-1}$ ;  $T$  is temperature,  $^{\circ}C$ .

For the simulation it was assumed that the billet was wholly heated to the temperature of  $1180^{\circ}C$ . The tool temperature was constant throughout the forming process and equalled  $150^{\circ}C$  for the rolls and  $500^{\circ}C$  for the chuck and the mandrel. Heat transfer coefficient between the tools and the material was assumed to be equal  $10000 W/m^2K$ .

The friction was modelled using the Tresca model, expressed with the following equation:

$$\tau = m k \quad (2)$$

where:  $\tau$  is shear stress on contact surface,  $k$  is a shear yield stress ( $k = \sigma_F/\sqrt{3}$ ),  $m$  is friction factor (set equal to  $m = 0.8$  for rolls

[18] and  $m = 0.4$  for mandrel). The contact between the chuck and the workpiece was determined by a glued model.

The workpiece was modelled using hexahedral-type elements. The base size of these elements was assumed to be 16 mm in the unformed part and 8 mm in the formed area, which is well illustrated by Figure 5. During calculations, remeshing occurred when effective strain exceeded 0.4.

The described process of rolling a hollow axle was simulated in 22500 steps. The calculation time for a 32-core computer was 2 weeks. This indicates the complexity of the numerical simulation.

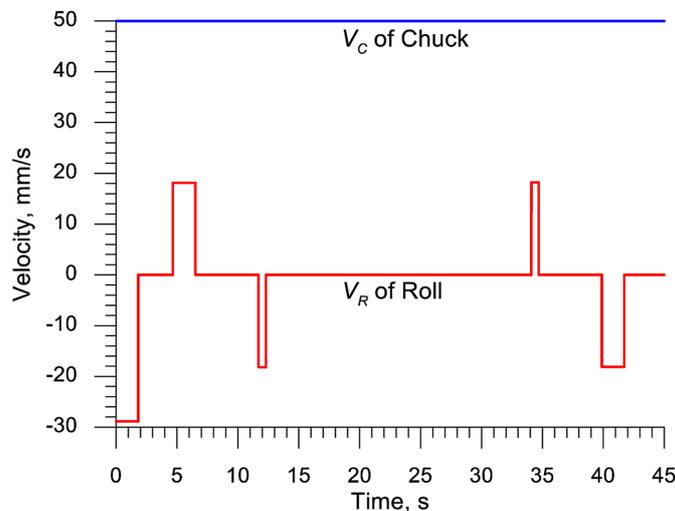


Fig. 4. Distributions of radial speed of the roll and the axial speed of the chuck during the process of skew rolling a hollow rail axle on a mandrel

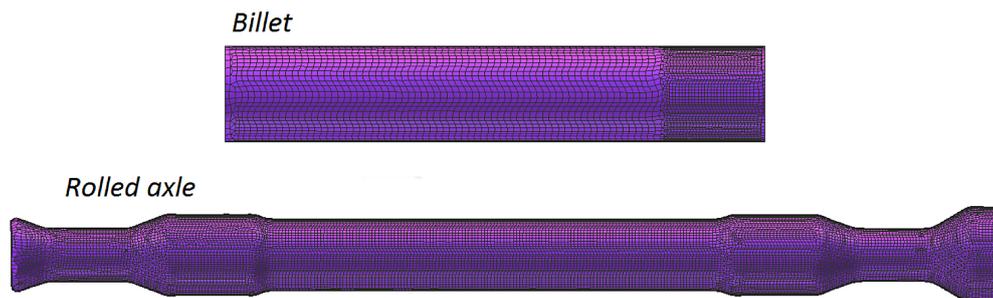


Fig. 5. View of the billet and the formed part, divided into hexahedral-type elements

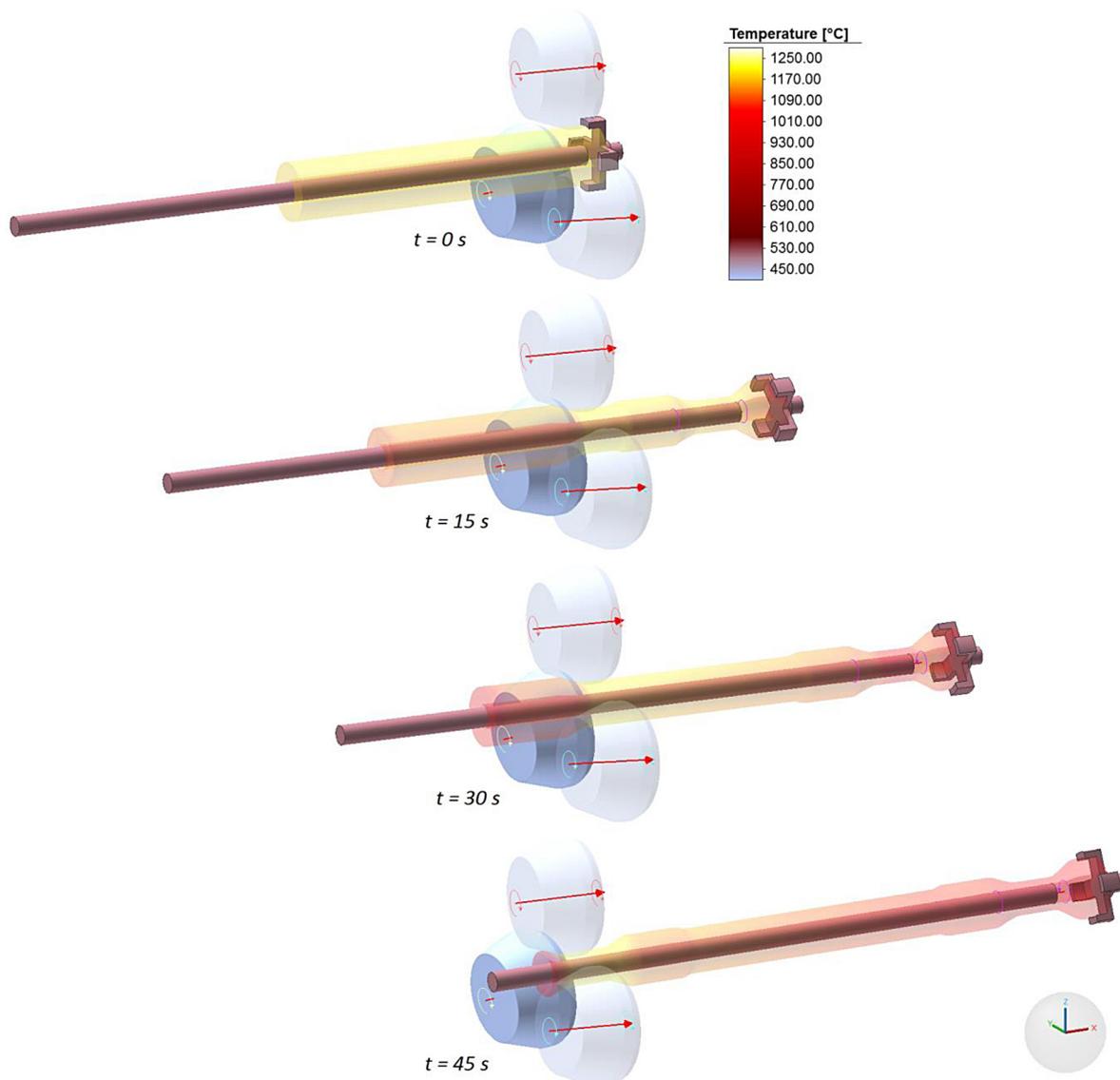
## OBTAINED RESULTS

The numerical simulation was deemed a success. The progression of the rolling process was shown in Figure 6. At the initial forming phase, the radially moving rolls compress the material on the mandrel. As a result of friction forces the material is set in ambulating motion both in axial and rotational direction. Along with the dislocation of the chuck, subsequent parts of the hollow axle are formed until its final shape.

Figure 7 presents a side and longitudinal-section view of the axle. It can be observed that the axial hole is cylindrical with  $\text{Ø}80$  mm diameter. The figure also presents the distribution of effective strain. The material was plastically

deformed throughout the entire volume of the axle due to the usage of a billet with the outer diameter ( $\text{Ø}240$  mm) significantly greater than the maximum diameter of the axle ( $\text{Ø}202$  mm). The deformations are placed annularly, with the greatest values located in the outer layers and the greatest in the inner ones. Such a distribution is caused by the rolls causing intensive material flow in the tangential direction. Such a distribution is typical for skew rolling processes [19].

The process of forming a hollow axle in accordance with the proposed concept is relatively long. One might therefore wonder if the material does not cool to such an extent that would hinder the forming process. Upon considering the temperature distributions shown in Figure 8, it can



**Fig. 6.** Progression of the skew rolling process of a hollow axle on a mandrel, temperature distribution given (in °C)

be stated that such fear is unwarranted, since the highest temperature (exceeding even the billet temperature) is reached by the material of the end step opposite to the chuck. This step is formed in the last stage of the process and it seems that the material ought to be cooler as a result of heat being transferred to the environment. However, during forming significant amounts of heat are produced as a result of the work of plastic strain and the work of friction being converted into it. As a result, material temperature in the forming zone exceeds the billet temperature.

One of the limitations to the skew rolling processes is the occurrence of cracks inside the rolled parts [20, 21]. The crack occurrence may be monitored by controlling the values of the so-called damage function. Figure 9 presents a

distribution of such a function, calculated in accordance with the normalised Cockcroft-Latham criterion [22, 23]. It is to be observed that the greatest values (reaching 2) of the function are located in the end steps, where the material is the most deformed. In order to prognosticate the risk of cracking occurrence it is necessary to know the value of critical damage, which is obtained in the calibrating test. It is important for the stress state in the calibrating test to be as similar as possible to the stress state of the analysed case of forming. In the case of three-roll skew rolling such a test is rotary compression of a disc in a channel [24]. Critical damage values for 42CrMo4 grade steel, determined in the course of the presented test, were shown in study [11]. For 1180 °C the critical damage value equals 3.2 and is significantly

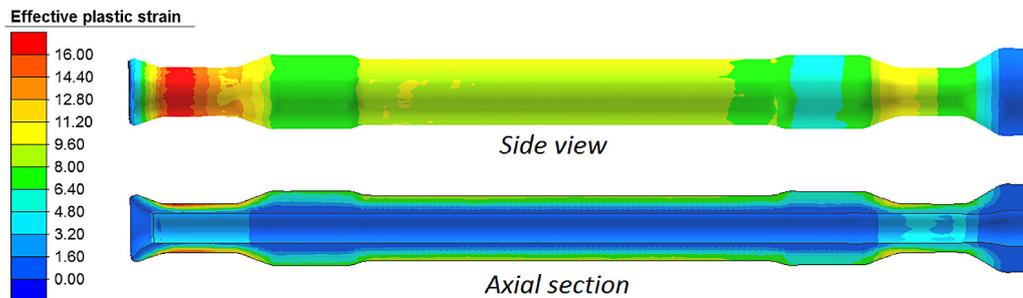


Fig. 7. Distributions of effective strain in a rolled hollow axle

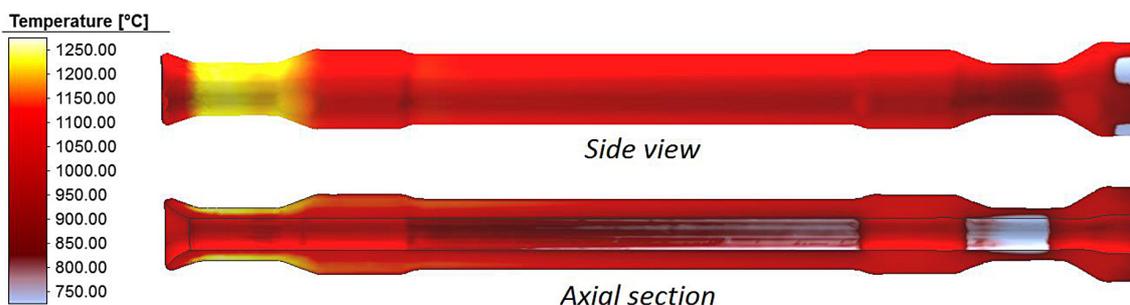


Fig. 8. Distributions of temperature in a rolled hollow axle

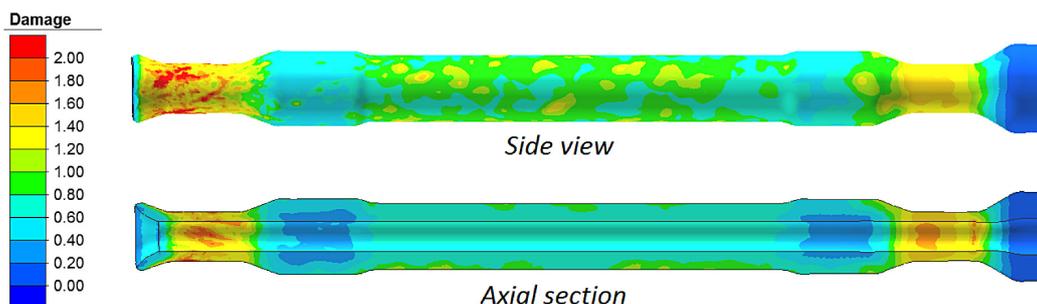


Fig. 9. Distributions of the damage function according to normalized Cockcroft-Latham criterion in a rolled hollow axle

greater than the maximum values observed in the analysed rolling process. Therefore it can be stated that in the analysed process of forming a hollow axle cracking should not occur.

Furthermore, numerical simulation also provided information on force parameters in the designed forming process. Figure 10 presents distributions of forces acting on the roll in the radial direction and on the chuck in the axial direction. The greatest forces on the roll occurred during forming of side steps, when the reduction of the billet diameter was the most intensive. These forces reached values to 1000 kN. The axial force on the chuck reached maximum values (up to 300 kN) during

the forming process of the central step of the axle. During forming of side steps the values of this force were smaller due to the axial material flow being more intensive. Considering the dimensions of the workpiece, the obtained maximum values of the forming forces ought to be deemed relatively small, which should result in a light construction of the industrial rolling mill.

Figure 11 presents a distribution of torque on a roll. This distribution is identical to the distribution of radial force. The maximum value of torque occurs during forming of side steps, where it reaches 50 kNm. The power of the engine acting on a single roll equals 314 kW. It can therefore be assumed

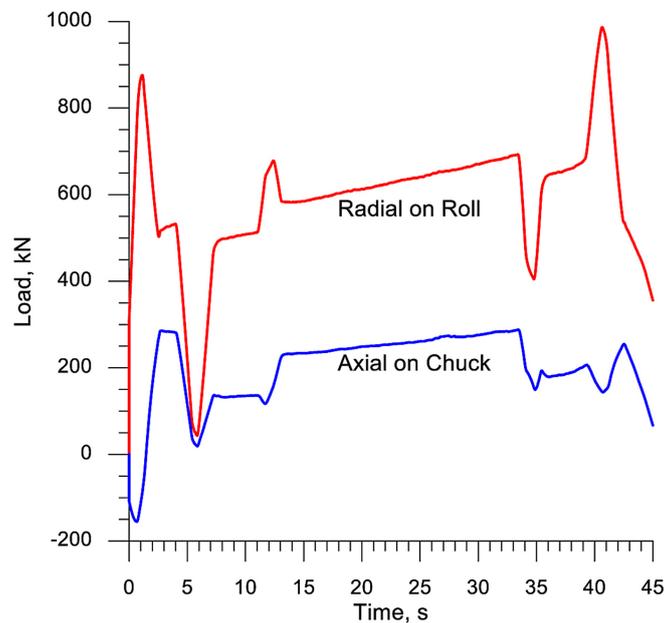


Fig. 10. Distributions of the forces acting on the roll and chuck during the process of rolling hollow rail axle on a mandrel

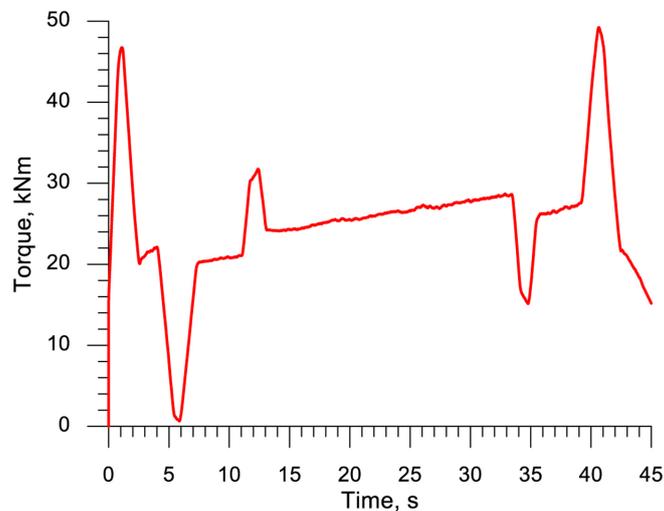


Fig. 11. Distribution of torque for a roll in the process of skew rolling of a hollow axle on a mandrel

that the industrial rolling mill used for manufacturing hollow axles on a moving mandrel ought to be powered by three engines with 350 kW each. Due to the fact that the maximum values of the torque appear temporarily, it is possible to decrease the engine power to 250 kW upon using flywheels.

## CONCLUSIONS

On the basis of the analysis performed it was stated that the method of CNC skew rolling may be used for manufacturing hollow rail axles with a cylindrical hole of constant diameter. The proper progression of the forming process depends on the usage of sleeve-shaped billet with the outer diameter exceeding the maximum diameter of the rolled part, whereas the inner diameter is greater than the diameter of the hole. During rolling, the outer shape of the axle is formed by three rolls, whereas the diameter of the hole is determined by a movable cylindrical mandrel. The operation of the aforementioned tools (rolls and mandrel) causes the material to intensively flow in the tangential direction, which results in an annular distribution of effective strain in the workpiece. The greatest values of strain can be observed in the outer layers of the axle, which is caused by friction forces on the roll-workpiece contact surface. Despite a relatively long forming time (c.a. 45 s) the material temperature remains in the range appropriate for hot working. This phenomenon is caused by the fact that the heat transported to the tools and environment is being compensated by the heat generated as a result of the work of friction and plastic strain. The hollow axle manufactured with the proposed method has a correct shape and is free of inner cracks. A characteristic trait of the rolling process is relatively low values of force parameter allowing one to manufacture hollow rail axles using a rolling mill with a light structure.

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